



## Final Virtual Event

27 October 2020 | 09-12 CET

Time	Topic
<b>Opening</b>	
09:00	Welcome & Introduction
09:10	What is TrustVehicle? Incl. book presentation
<b>TrustVehicle: main results and demonstrations</b>	
09:20	Assessing Driver Behaviour and Trust for Mixed L3AD Scenarios on a Driving Simulator <i>Philipp Clement, AVL</i>
09:30	Driver Face Monitoring and Identification <i>Caterina Nahler, Infineon Austria</i>
09:40	Concept, Optimization and Testing of Sensors Cleaning Functions under Adverse Weather <i>Frederic Bretagnol, Ahmed Aaddaj El Oudrhiri, Valeo Vision</i>
09:55	Sensor Monitoring and Self-Cleaning Sensors for a Passenger Vehicle <i>Daniel Åhlund, Elias Marel, Volvo Cars</i>
10:10	Building Trust in Level 3 Autonomous Commercial Vehicles - Smooth Trajectory Planning <i>Assoc. Prof. Ahu Ece Hartavi Karci, Tarek, Kabbani, University of Surrey</i>
10:20	Heavy Truck-Trailer Reverse Parking Feature <i>Ersun Sözen, Ford Otosan</i>
10:35	HMI for an Electric Bus driving automatically to the Charging Station <i>Mikko Tarkiainen, VTT   Sami Sahimäki, Linkker</i>
10:50	Sensor Data Fusion Platform <i>Lorenzo Giraudi, Ideas&amp;Motion</i>
11:00	Light Commercial Vehicle Sensor Fusion Development <i>Kemal Rodoplu, Tofas</i>
11:15	Q&A
<b>Sister projects</b>	
11:30	ART-04 Cluster Introduction
11:35	interACT project <i>Marc Wilbrink, DLR</i>
11:45	BRAVE project <i>Ingrid Skogsmo, VTI Sweden</i>
11:55	<b>Summary and Closure</b>